

Lesson 19 Remote Control - Introduction to WEBUI (Recommended)

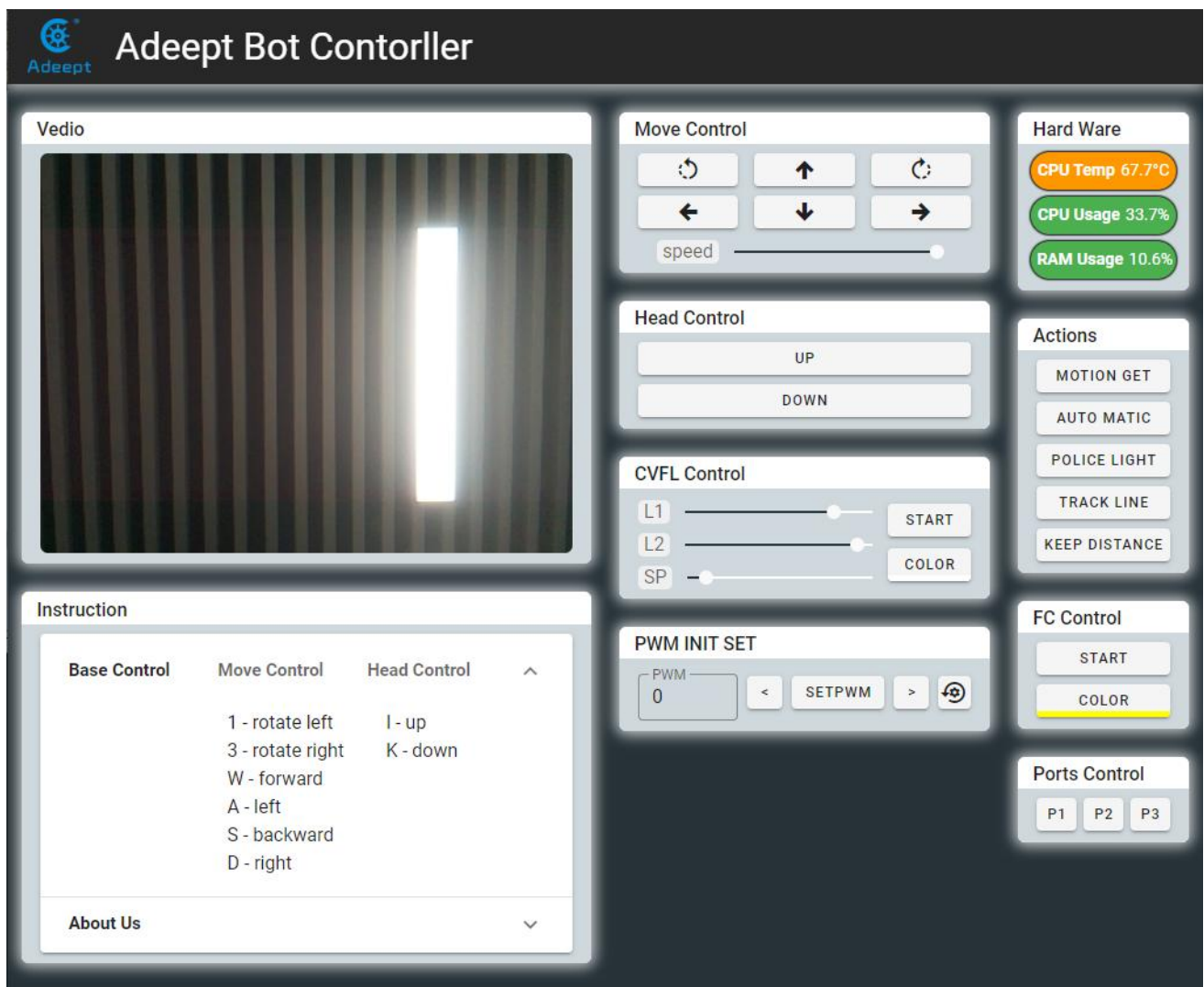
19.1 Overview

In this lesson, we will explore the Web - based User Interface (WEBUI) for remote - controlling a robot. This WEBUI provides a convenient and intuitive way to interact with the robot, enabling users to control various aspects such as movement, arm operations, and sensor - based functions.

19.2 Getting Access to Web Controller

- A web controller is a web interface to control the robot product to perform various actions and it can be applied on any device that is able to run a browser, including PC, mobile phones, tablets, etc.
- If you've completed all installations based on the instructional document, it will be quite easy to open a web controller.
 1. Check that your device is under the same LAN with the Raspberry Pi.
 2. Obtain the Raspberry Pi's IP address.
 3. Open a web browser (recommended to use Chrome in case of any possible incompatibility with other browsers), enter the Raspberry Pi's IP address with the port :5000, for instance:
192.168.3.130:5000

Then the web controller will be loaded into the browser.



Modules on the web controller may vary from products. Most of them are explained below with the method for application. You can check modules on your web controller accordingly to better understand their functions and how to use them.

19.3 Principle Introduction

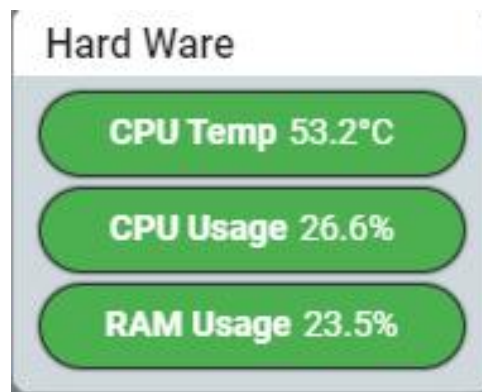
1. Video Module

Display the image captured by the camera.



2. Hard Ware Module

Display the CPU temperature, as well as the usage of CPU and RAM in real time.



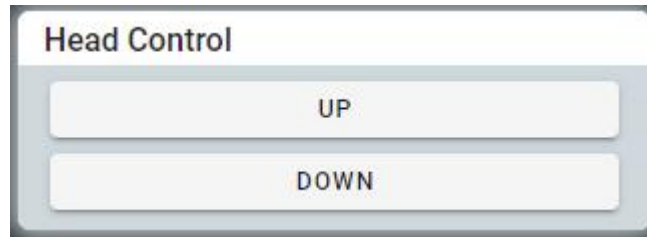
3. Move Control Module

Control the movement of the robot towards the front, back, left, right, forward left, forward right, backward left, backward right, rotate left and rotate right.



4. Head Control Module

Control the movement of the robotic head.



5. Actions Module

The switches for some functions, such as motion detection, automatic obstacle avoidance, warning lights, speech recognition, and line tracking.



6. FC Control Module

Control the color detection function on/off and color setup.



7. PWM INIT SET Module

Adjust the angle of the servo motor.



8. Ports Control Module

Control the on/off of three LED lights.



The operation instructions are as follows:

	Button	Instruction	Describe
Move Control	FORWARD/The W key on the keyboard	forward/DS	move forward
	BACKWARD/The S key on the keyboard	backward/DS	move backward
	LEFT/The A key on the keyboard	left/TS	move left
	RIGHT/The D key on the keyboard	right/TS	move right
	SpinLeft/The 1 key on the keyboard	rotate-left/DS	Rotate left
	SpinRight/The 3 key on the keyboard	rotate-right/DS	Rotate right
	speed	wsB X	Adjusting speed
Head Control	UP/The I key on the keyboard	up/UDstop	The robotic head turns up
	DOWN/The K key on	down/UDstop	The robotic head

	the keyboard		turns down
CVFL Control	START	CVFL/stopCV	Switch video tracking line function
	COLOR	CVFLColorSet 0/CVFLColorSet 255	Switch to search for white lines on black or black lines on white.
	L1	CVFLL1 X	Set the height of L1 auxiliary line
	L2	CVFLL2 X	Set the height of L2 auxiliary line
PWM INIT SET	NUM		Servo connection channel number
	<	SiLeft X	Click the button to control the x-channel servo to rotate clockwise.
	>	SiRight X	Click the button to control the x-channel servo to rotate counterclockwise
	SETPWM	PWMMS X	Click the button to control the x-channel servo to 90 degrees
Hard Ware	CPU Temp		Shows the temperature of the Raspberry Pi CPU
	CPU Usage		Shows the usage of the Raspberry Pi CPU

	RAM Usage		Shows the usage of the Raspberry Pi memory
Actions	MOTION GET	motionGet/stopCV	Switch to monitor mode, the robot stops moving and reacts to the moving objects detected by the camera, which are framed in the video module.
	AUTO MATIC	automatic/automaticOff	Switch to automatic obstacle avoidance mode
	POLICE LIGHT	police/policeOff	Make the WS2812 LED lights on the robot flash alternately in red and blue.
	TRACK LINE	trackLine/trackLineOff	Implement line tracking function using a 3-channel infrared module.
	KEEP DISTANCE	keepDistance/keepDistanceOff	Implementing a distance maintenance function using an ultrasonic module
	START	findColor/stopCV	Turn on/off the color detection function.

FC Contorl	COLOR	{'title': 'findColorSet', 'data': [r,g,b]}	Select the color to be detected
Ports Control	P1	Switch_1_on/Switch_2_off	Control the LED1 light to turn on and off
	P2	Switch_2_on/Switch_2_off	Control the LED2 light to turn on and off
	P3	Switch_3_on/Switch_3_off	Control the LED3 light to turn on and off